

1. (JPE, September 1993). Solve the system

$$\begin{pmatrix} 0.001 & 1.00 \\ 1.00 & 2.00 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1.00 \\ 3.00 \end{pmatrix}$$

using the LU decomposition with and without partial pivoting and chopped arithmetic with base  $\beta = 10$  and  $t = 3$  (i.e., work with a three digit mantissa). Obtain computed solutions  $(x_c, y_c)$  in both cases. Find the exact solution, compare, make comments.

2. (JPE, May 2003). Consider the system

$$\begin{pmatrix} \varepsilon & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Assume that  $|\varepsilon| \ll 1$ . Solve the system by using the LU decomposition with and without partial pivoting and adopting the following rounding off models (at all stages of the computation!):

$$\begin{aligned} a + b\varepsilon &= a && (\text{for } a \neq 0), \\ a + b/\varepsilon &= b/\varepsilon && (\text{for } b \neq 0). \end{aligned}$$

Find the exact solution, compare, make comments.

3. (JPE, September 1997). Show that, given a matrix  $A \in \mathbb{R}^{n \times n}$ , one can choose vectors  $b$  and  $\Delta b$  so that if

$$\begin{aligned} Ax &= b \\ A(x + \Delta x) &= b + \Delta b \end{aligned}$$

then

$$\frac{\|\Delta x\|_2}{\|x\|_2} = \kappa_2(A) \frac{\|\Delta b\|_2}{\|b\|_2}$$

Explain the significance of this result for the ‘optimal’ role of condition numbers in the sensitivity analysis of linear systems.

(Hint: use the SVD theorem to show that it is enough to consider the case where  $A$  is a diagonal matrix.)

4. (JPE, combined May 1997 and May 2008)

(a) Compute the condition numbers  $\kappa_1$ ,  $\kappa_2$  and  $\kappa_\infty$  for the matrix

$$A = \begin{pmatrix} 1 & 2 \\ 1.01 & 2 \end{pmatrix}$$

(b) Show that for every non-singular  $2 \times 2$  matrix  $A$  we have  $\kappa_1(A) = \kappa_\infty(A)$ .