

1. Prove properties 1, 6, and 8 of condition numbers listed in Proposition 12.8.
2. (JPE, September 1997). Show that, given a matrix $A \in \mathbb{R}^{n \times n}$, one can choose vectors b and Δb so that if

$$Ax = b$$

$$A(x + \Delta x) = b + \Delta b$$

then

$$\frac{\|\Delta x\|_2}{\|x\|_2} = \kappa_2(A) \frac{\|\Delta b\|_2}{\|b\|_2}$$

Explain the significance of this result for the ‘optimal’ role of condition numbers in the sensitivity analysis of linear systems.

(Hint: use the SVD theorem to show that it is enough to consider the case where A is a diagonal matrix.)

3. (JPE, September 2002). Consider a linear system $Ax = b$. Let x^* be the exact solution, and let x_c be some computed approximate solution. Let $e = x^* - x_c$ be the error and $r = b - Ax_c$ the residual for x_c . Show that

$$\frac{1}{\kappa(A)} \frac{\|r\|}{\|b\|} \leq \frac{\|e\|}{\|x^*\|} \leq \kappa(A) \frac{\|r\|}{\|b\|}$$

Interpret the above inequality for $\kappa(A)$ close to 1 and for $\kappa(A)$ large.

4. (JPE, May 1997). Compute the condition numbers κ_1 , κ_2 and κ_∞ for the matrix

$$A = \begin{pmatrix} 1 & 2 \\ 1.01 & 2 \end{pmatrix}$$

For extra credit: show that for typical 2×2 matrices A we have $\kappa_1(A) = \kappa_\infty(A)$. What exactly does ‘typical’ mean here?